
上海理工大学

光电信息与计算机工程学院

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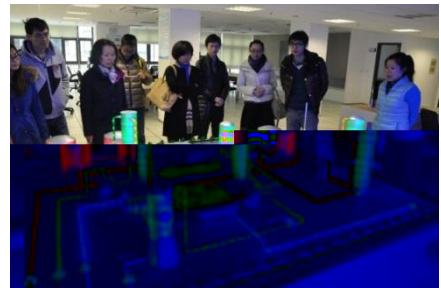
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IEEE ITSC 2014

Obstacle recognition for ADAS using stereovision and snake models

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